

Preferred type only in conjunction with flange type 1



Standard Optical	Sendix 58	58 / 5878 (Shaft / Hollow shaft)	PROFINET IO	
Mounting accessory fo	or shaft encoders			Order No.
Coupling		Bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24 Bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.3		8.0000.1101.0606 8.0000.1101.1010
Mounting accessory fo	or hollow shaft encoders			
<b>Cylindrical pin, long</b> for torque stops	8[0,3] 5[0,2]	With fixing thread		8.0010.4700.0000
Connection technology	Y			
Connector, self-assemb	ly (straight)	Coupling M12 for Port 1 and Port 2 Connector M12 for power supply		05.WASCSY4S 05.B8141-0
Cordset, pre-assembled	1	M12 for Port 1 and Port 2, 2 m [6.56'] PUR cable M12 for power supply, 2 m [6.56'] PUR cable		5.00.6031.4411.002M 5.00.6061.6211.002M

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection\_technology

#### Technical data

Mechanica	l characteristics	
Max. speed	IP65 up to 70°C [158°F] IP65 up to T <sub>max</sub> IP67 up to 70°C [158°F] IP67 up to T <sub>max</sub>	9 000 min <sup>-1</sup> , 7 000 min <sup>-1</sup> (continuous) 7 000 min <sup>-1</sup> , 4 000 min <sup>-1</sup> (continuous) 8 000 min <sup>-1</sup> , 6 000 min <sup>-1</sup> (continuous) 6 000 min <sup>-1</sup> , 3 000 min <sup>-1</sup> (continuous)
Starting torqu	e - at 20°C [68°F] IP65 IP67	< 0.01 Nm < 0.05 Nm
Moment of ine	ertia Shaft version Hollow shaft version	3.0 x 10 <sup>-6</sup> kgm <sup>2</sup> 6.0 x 10 <sup>-6</sup> kgm <sup>2</sup>
Load capacity	of shaft radial axial	80 N 40 N
Weight		approx. 0.50 kg [17.64 oz]
Protection ac	c. to EN 60529	
	housing side shaft side	IP67 IP65, opt. IP67
EX approval fo	or hazardous areas	optional Zone 2 and 22
Working temperature range		-40°C +85°C [-40°F +185°F]
Material	shaft/hollow shaft flange housing	stainless steel aluminium zinc die-cast housing
Shock resista	<b>nce</b> acc. EN 60068-2-27	2500 m/s², 6 ms
Vibration resistance acc. EN 60068-2-6		100 m/s², 55 2000 Hz

Electrical characteristics					
Power supply	10 30 V DC				
Power consumption (no load)	max. 200 mA				
Reverse polarity protection of the power supply (+V)	yes				
UL approval	File 224618				
CE compliant acc. to	EMC guideline 2004/108/EC				
RoHS compliant acc. to	guideline 2011/65/EU				

Device characteristics					
Singleturn resolution		1 65535 (16 bit), scaleable			
Default value		8192 (13 bit)			
Total resolution		scaleable from 1 up to 65535 (13 bit)			
Code		binary			
Protocol		PROFINET IO			
Link 1 and 2, LED (green	/ yellow				
two coloured	green	active link			

3	
yellow	data transfer

Error LED (red) / PWR LED (green)

Functionality see manual

### Ezturn software for PROFINET IO (supplied with the encoder)

- Monitoring of cyclic data (e.g. position, speed)
- Monitoring of acyclic data (e.g. IMO, electronic name plate, encoder parameters, warnings and error messages, preset)
- Setting of preset values
- Firmware updates via the bus



### Standard Optical

### Sendix 5858 / 5878 (Shaft / Hollow shaft)

### **PROFINET IO**

#### **General information about PROFINET IO**

The PROFINET encoder implements the Encoder Profile 4.1. (according to the specification Encoder Version 4.1 Dec 2008")

It permits scaling and preset values, as well as many other additional parameters to be programmed via the PROFINET-Bus.

When switching on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure, or taken over by the controller in the start-up phase.

Position, speed and many other states of the encoder can be transmitted.

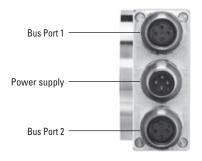
#### **PROFINET IO**

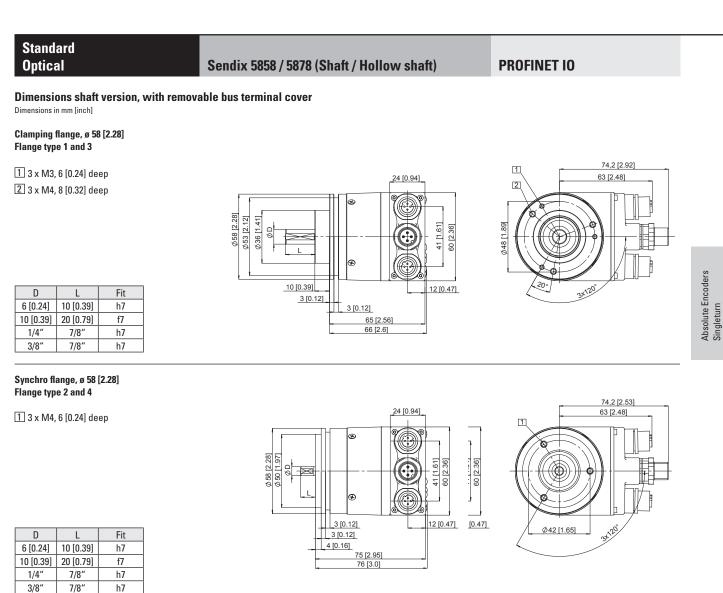
The complete encoder profile according to Profile Encoder Version 4.1 as well as the Identification & Maintenance functionality Version 1.16 has been implemented. IM blocks 0, 1, 2, 3 and 4 are supported.

The <u>M</u>edia <u>R</u>edundancy <u>P</u>rotokoll is implemented here. Basically, the advantage of MRP is that the functionality of the components, which are wired in a ring structure, is maintained in case of a failure or of a breakage of the wires in any location.

#### **Terminal assignment bus**

Int	terface	Type of connection	Function	M12 connector					
			Bus Port 1	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	12
				Abbreviation:	TxD+	RxD+	TxD-	RxD-	D coded
				Pin:	1	2	3	4	4 3
			Power	Signal:	Voltage +	_	Voltage –	_	4 3
	С	2	supply	Abbreviation:	+ V	-	0 V	-	
		(3 x M12 connector)		Pin:	1	2	3	4	1 2
			Bus Port 2	Signal:	Transmit data+	Receive data+	Transmit data -	Receive data -	12
				Abbreviation:	TxD+	RxD+	TxD-	RxD-	D coded
				Pin:	1	2	3	4	4 3

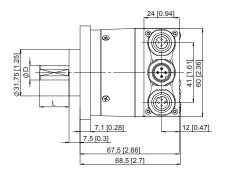


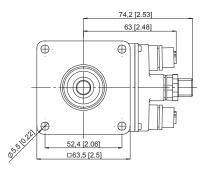


Square flange, 🗌 63.5 [2.5]	

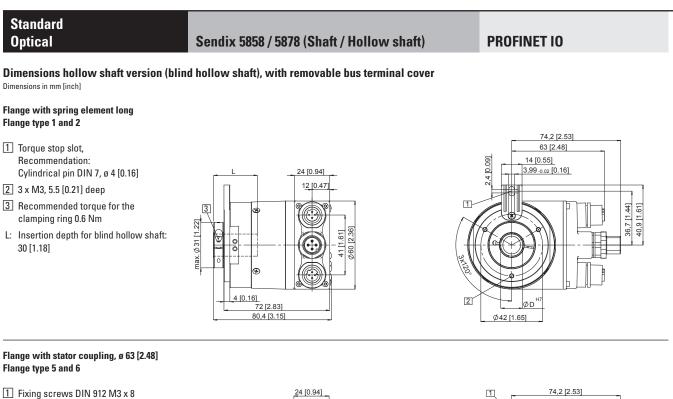
Flange type 5 and 7

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7





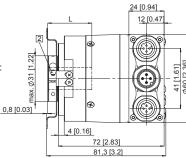
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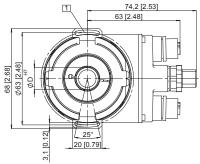


2 Recommended torque for the clamping ring 0.6 NmL: Insertion depth for blind hollow shaft:

30 [1.18]

(Washer included in delivery)





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#### Flange with stator coupling, ø 65 [2.56] Flange type 3 and 4

- 1 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]

